



























## Models and Options

Model		RHA005 Page →9	RHA010 Page →11	RHB010 Page →13	RHA020 Page →15	RHB020 Page →17	RHA040 Page →19	RHA080 Page →21	RHA160 Page →23	RHA230 Page →25
Master plate: <b>M</b>										
Tool plate: <b>T</b>										
Mass (option excluded)	<b>M</b>	160g	210g	295g	580g	650g	1010g	1840g	5600g	8300g
	<b>T</b>	90g	120g	225g	320g	385g	570g	890g	2800g	3800g
Payload		5 kg	10 kg	10 kg	20 kg	20 kg	40 kg	80 kg	160 kg	230 kg
Number of ports for connector for air (Size)		4 (M5)	6 (M5)	6 (Rc1/8)	6 (M5)	6(Rc1/8)	8 (Rc1/8)	12 (Rc1/8)	8 (Rc3/8)	10 (Rc3/8)
Connector for air with check valve <b>C</b>			●		●		●	●	●	●
Expansion of connector for air <b>A0</b> Page →27			●	●	●	●	●	●	●	●
Sensor for connecting/disconnecting <b>SN / SP</b> Page →28					●	●	●	●	●	●
Electric connector <b>E0/ E00</b> Page →29		●	●	●	●	●	●	●	●	●
Circular electric connector <b>E4</b> Page →30					●	●	●	●	●	●
Circular electric connector <b>E5</b> Page →31					●	●	●	●	●	●
Remote sensor <b>RN / RP / R</b> Page →33			●	●	●	●	●	●	●	●
Remote sensor <b>RN4 / RP4 / R4</b> Page →35		●	●	●	●	●	●	●	●	●

● Option available.

● Refer to the respective pages for the details and model numbers of the master plate, tool plate and their options.

● Contact Pascal for an adapter plate for mounting robots.